Kawasaki Heavy Industries, Ltd

Robot Business Division

Tokyo Head Office/Robot Division 1-14-5, Kaigan, Minato-ku, Tokyo 105-8315, Japan Fax: +81-3-3437-9880 Phone: +81-3-3435-2501

Akashi Works/Robot Division 1-1, Kawasaki-cho, Akashi, Hyogo 673-8666, Japan Phone: +81-78-921-2946 Fax: +81-78-923-6548

Nishi-Kobe Works/Robot Division 234, Matsumoto, Hasetani-cho, Nishi-ku, Kobe, Hyogo 651-2239, Japan Phone: +81-78-915-8247 Fax: +81-78-915-8239

Global Network

Kawasaki Robotics (USA), Inc. 28140 Lakeview Drive, Wixom, MI 48393, U.S.A. Phone: +1-248-446-4100 Fax: +1-248-446-4200

Kawasaki Robotics (UK) Ltd. Unit 4 Easter Court, Europa Boulevard, Westbrook Warrington Cheshire, WA5 7ZB, United Kingdom Fax: +44-1925-71-3001 Phone: +44-1925-71-3000

Kawasaki Robotics GmbH Im Taubental 32, 41468 Neuss, Germany Phone: +49-2131-34260 Fax: +49-2131-3426-22

Kawasaki Robotics Korea, Ltd. 43, Namdong-daero 215beon-gil, Namdong-gu, Incheon, 21633, Korea Phone: +82-32-821-6941 Fax: +82-32-821-6947

Kawasaki Robotics (Tianjin) Co., Ltd. 1.2/F, Building 6, No.19 Xinhuan Road, TEDA, China Phone: +86-22-5983-1888 Fax: +86-22-5983-1889

Taiwan kawasaki Robot Center 3F, No.31, Ln.216, Gongyuan Rd., Hsinchu City 30069. Taiwan(R.O.C) Phone: +886-3-562-0518

Kawasaki Motors Enterprise (Thailand) Co., Ltd. (Rayong Robot Center) 119/10 Moo 4 T.Pluak Daeng, A.Pluak Daeng, Rayong 21140 Thailand Fax: +66-38-955-145

Phone: +66-38-955-040-58

Singapore Kawasaki Robot Center 100G Pasir Panjang Road #06-10 Singapore 118523 Phone: +65-6513-3145

Kawasaki Heavy Industries (India) Pvt. Ltd. Robot Division Plot No. 136, Sector-37, Pace City 1, Gurgaon, 122101 Haryana, India Phone: +91-124-437-1845

Kawasaki Robotics website https://robotics.kawasaki.com/

Kawasaki Robotics brand site XYZ https://robotics.kawasaki.com/ja1/xyz/en/



Kawasaki Robostage (showroom) https://robotics.kawasaki.com/ja1/robostage/en.html



Kawasaki Robot

Wafer Transfer Robots



- For those persons involved with the operation / service of your system, including Kawasaki Robot, they must strictly observe all safety regulations at all times. They should carefully read the Manuals and other related safety documents.
- Products described in this catalogue are general industrial robots. Therefore, if a customer wishes to use the Robot for special purposes, which might endanger operators or if the Robot has any problems, please contact us. We will be pleased to help vou.
- Be careful as Photographs illustrated in this catalogue are frequently taken after removing safety fences and other safety devices stipulated in the safety regulations from the Robot operation system.



ISO certified in Akashi Works and Nishi-Kobe Works.





Wafer transfer robots

Wafer Transfer Robots

Kawasaki has the No.1 market share in the wafer transfer clean robots. A single robot can access 2 and 3 FOUPs of EFEM without a track. The robots are compatible with SEMI-F47 and SEMI-S2 standards.

NTS series



Features

Accessible to 2 and 3 FOUP FEM.

Wafer transfer

Smooth and accurate operations thanks to the specially designed drive system.



TTS series



Wafer transfer

High-speed handling in high and low positions thank to a unique high-rigidity telescopic mechanism.



Smooth and accurate operations thanks to original driving mechanism.

Compliant with SEMI-F47 and S-2 standards.

NTS10/NTS20

Standard Specifications /

Туре		Horizontal articulated type	
Degree of freedom (axes)		4/5	
Max. reach (mm)		1,066	
Position repeatability*1 (mm)		±0.1 (Wafer Center)	
Motion range	θ1axis (rotation JT2) (°)	340	
	Zaxis (up-down JT3) (mm)	470	
	θ2axis (rotation JT4) (°)	340	
	H1axis (rotation JT6) (°)	340	
	H2axis (rotation JT7) (°)	— /340	
Mounting		Floor	
Controller/Power requirements		D60/1.0kVA	

*1: Conforms to ISO9283

Features

Unique telescopic mechanism to cover high and low positions.

Compliant with SEMI-F47 and S-2 standards.

TTS10/TTS20

Standard Specifications

Туре		Telescopic horizontal articulated type			
Degree of freedom (axes)		4/5			
Max. reach (mm)		1,066			
Position repeatability*1 (mm)		±0.1 (Wafer Center)			
Motion range	θ1axis (rotation JT2) (°)	340			
	Zaxis (up-down JT3) (mm)	740			
	heta2axis (rotation JT4) (°)	340			
	H1axis (rotation JT6) (°)	340			
	H2axis (rotation JT7) (°)	— /340			
Mounting		Floor			
Controlle	r/Power requirements	D60/1.0kVA			
Controlle	r/Power requirements	D60/1.0kVA			

*1: Conforms to ISO9283

Layout Example







D60/D61

Standard Specifications

		D60	D61	
	NTS series	W320×D130×H300	W445×D130×H429	
	TTS series	W395×D130×H300	W565×D130×H429	
Number of controlled axes		Max. 7 axes	Max. 12 axes	
Driving system		Full digital servo system		
Types of motion	Teach mode	Joint (operating) mode / base coordinate system		
control	Repeat mode	Joint interpolation, linear interpolation, offset linear interpolation		
Programming		Manual, semi-automatic, full-automatic teaching		
External signals		External emergency stop, safety fence, external stop		
	Hardware	RS232C x 1	RS232C x 2	
Communications*1		Ethernet		
commonications	Software	K-Utility (Kawasaki's original communication command for clean robots)		
Power	Voltage	Single phase, AC208 V ±10%, 50/60 Hz		
requirements	Standard	SEMI F47		
Ambient remperature for operation (°C)		5 - 40 ^{*2}		
Mass (kg)		14	20	

*1: Customized commands may be available. Contact Kawasaki *2: Contact Kawasaki for operations outside the specified range



Standard software

Enables operations for wafer transfer. robot operations and monitoring of operating conditions.

KMTerm

By connecting with the robot controller, the KMTerm allows parameter setting, information display and data backup.

KSUtility Lite

The KSUtility Lite enables the robot to be operated from the host PC.

KR3D

KRET

ease.

KSUtility

off-line with ease.



Features

High-speed alignment is possible (only 2.5 seconds for alignment).





*The D61 controller has a cabinet size of different dimensions

Features

D60

The D60 and D61 are compact controllers for wafer transfer robots. (D60 for single arm and D61 for two arms).

- The D60 and D61 can control up to 7 axes and up to 12 axes respectively.
- Both are compliant with SEMI standard and CE marking, and can be used anywhere in the world.

Optional software

Optional software allows the users to perform layout studies and simulation for tact time on their own PC.

Designing of layout inside the equipment and operational paths can be done with

This software enables the robot to be operated from the host PC.

Robot operations can be performed

